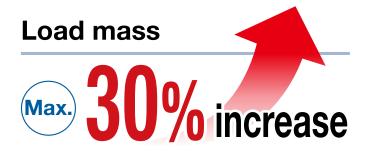
# Mechanically Jointed Rodless Cylinder

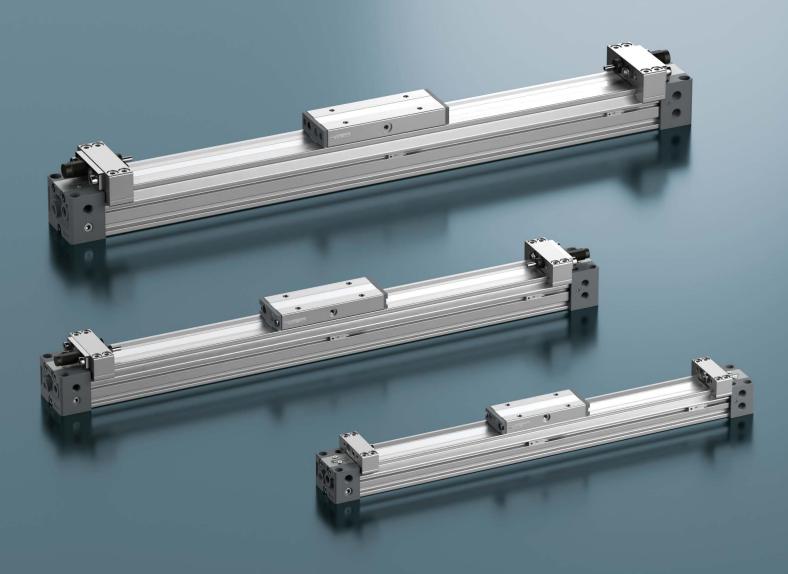


Basic Type: Ø25, Ø32, Ø40





Same mounting dimensions as the existing MY1B







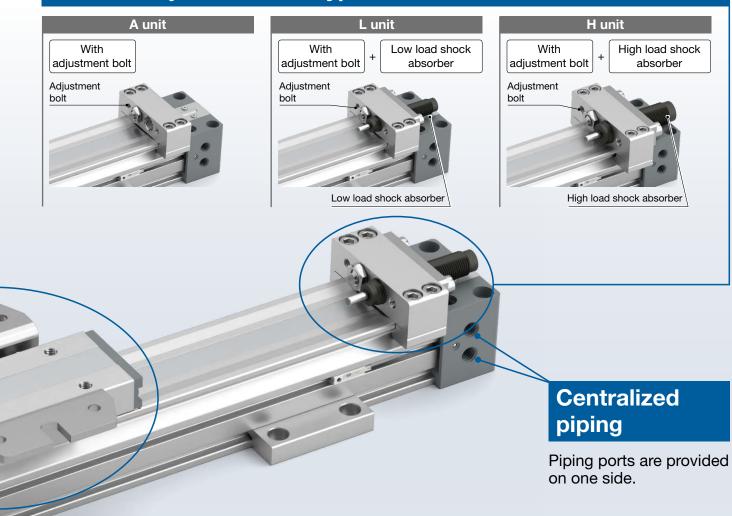
## Mechanically Jointed Rodless Cylinder/Basic Type MY1B Series



**SMC** 

1

# Built-in adjustment bolt and shock absorber, 3 stroke adjustment unit types

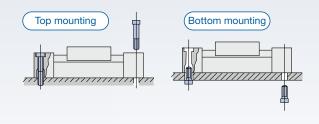


# Auto switches can be mounted from the front. Contributes to reduction in mounting time



## 2 mounting types, Space saving

This does not change the overall length dimension.



#### **Series Variations**

Series	Guide type	Guide	Din in a true	Во	re size [r	nm]	Air arabian	Stroke	Ciala accompand	Floating	Mada ta audau
Series		Piping type	25	32	40	Air cushion	adjustment unit	Side support	bracket	Made to order	
New MY1B-Z1	Basic	Centralized piping								Shock absorber soft type	
WIT IB-ZI	Dasic	Standard piping								RJ series mounted  • Helical insert thread	

**SMC** 

Mechanically Jointed Rodless Cylinder/Basic Type MY1B Series

## **Related Products**

#### Deceleration Controller DAS Series





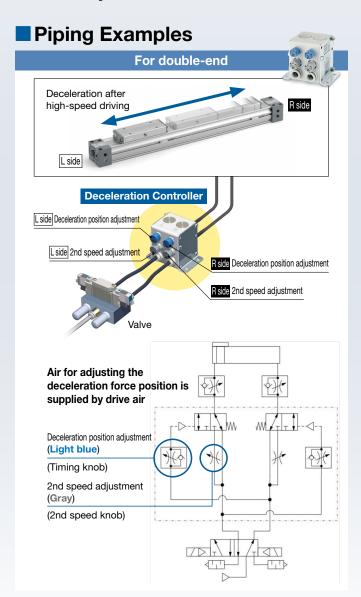
2-speed control reduces cycle time.
Allows for the impact relaxation of the stroke end

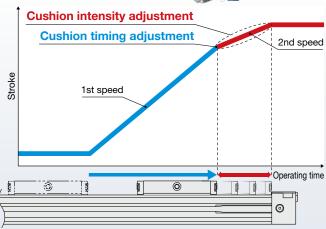
Allows for the 2-speed control of cylinders

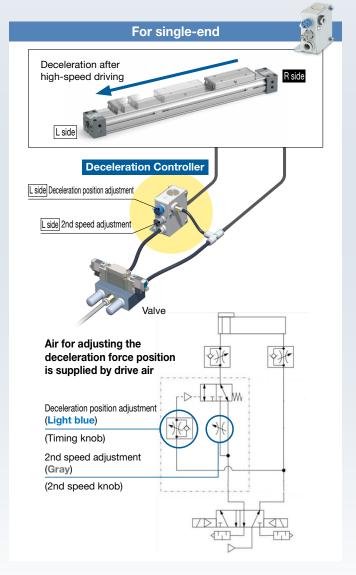
The deceleration position (cushion timing) and

2nd speed (cushion intensity)

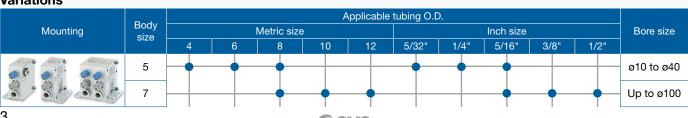
can be adjusted.







#### **Variations**



# CONTENTS

# Mechanically Jointed Rodless Cylinder/Basic Type MY1B Series



Prior to Use p. 5
Model Selection p. 7
How to Orderp. 9. 9
Specifications, Piston Speed, Stroke Adjustment Unit
Theoretical Output, Weight, Cushion Capacity p. 1
Construction p. 12
Dimensions: Standard Type/Centralized Piping Type p. 13
Stroke Adjustment Units p. 14
Accessory Brackets (Option) p. 16
Side Supports, Guide for Side Support Application p. 17
Floating Brackets p. 18
Auto Switch Mounting p. 19
Specific Product Precautions p. 20
Safety Instructions Back cove

# MY1B Series Prior to Use

#### Maximum Allowable Moment/Maximum Load Mass

Model	Bore size	Maximum a	allowable mo	ment [N·m]	Maximum load mass [kg]				
Model	[mm]	M1 M2 M3		m1	m2	m3			
	25	13.0	1.6	3.9	37.7	5.8	7.0		
MY1B	32	26.0	3.1	7.8	52.0	8.0	11.4		
	40	52.0	6.2	15.6	68.9	10.6	18.2		

The above values are the maximum values for allowable moment and load mass. Refer to each graph regarding the maximum allowable moment and maximum load mass for a particular piston speed.

#### **Caution on Design**

- · We recommend installing an external shock absorber when the cylinder is combined with another guide (connection with floating bracket, etc.) and the maximum allowable load is exceeded.
- · If the product is operated with a guide load factor which exceeds the standard value, malfunction may occur due to damage to the end cover and bearings. Therefore, be sure to confirm that the guide load factor is 1 or less.

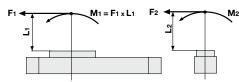
#### Load mass [kg]

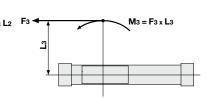






#### Moment [N·m]





#### <Calculation of guide load factor>

- 1. Maximum load mass (1), static moment (2), and dynamic moment (3) (at the time of impact with stopper) must be examined for the selection calculations.

  \* To evaluate use 1)a (average speed) for (1) and (2), and 1) (collision speed 1) = 1.4.1(a) for (3). Calculate m may for (1) from the maximum load mass graph (my, max ma) and
  - \* To evaluate, use Va (average speed) for (1) and (2), and V (collision speed V = 1.4 Va) for (3). Calculate m max for (1) from the maximum load mass graph (m<sub>1</sub>, m<sub>2</sub>, m<sub>3</sub>) and M max for (2) and (3) from the maximum allowable moment graph (M<sub>1</sub>, M<sub>2</sub>, M<sub>3</sub>).

- \*1 Moment caused by the load, etc., with cylinder in resting condition
- \*2 Moment caused by the load equivalent to impact at the stroke end (at the time of impact with stopper)
- \* Depending on the shape of the workpiece, multiple moments may occur. When this happens, the sum of the load factors (Σα) is the total of all such moments.
- 2. Reference formula [Dynamic moment at the time of impact]

Use the following formulae to calculate dynamic moment when taking stopper impact into consideration.

m: Load mass [kg]

F: Load [N]

FE: Load equivalent to impact

(at the time of impact with stopper) [N]

Va: Average speed [mm/s]

M: Static moment [N·m]

 $\upsilon = 1.4\upsilon a \text{ [mm/s] } F_E = 1.4\upsilon a \cdot \delta \cdot \text{m} \cdot \text{g}$ 

∴ **M**E =  $\frac{1}{3}^{*4}$ ·FE· L<sub>1</sub> = 4.57 $\Im$ 0a $\Im$ mL<sub>1</sub>

υ: Collision speed [mm/s]

L<sub>1</sub>: Distance to the load center of gravity [m]

M<sub>E</sub>: Dynamic moment [N·m]

δ: Bumper coefficient

With air cushion = 1/100

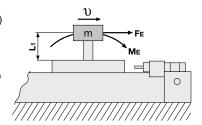
With shock absorber = 1/100

g: Gravitational acceleration (9.8 m/s²)



\*4 Average load coefficient (=  $\frac{1}{3}$ ): For averaging the maximum load moment at the time of impact with stopper according to service life calculations

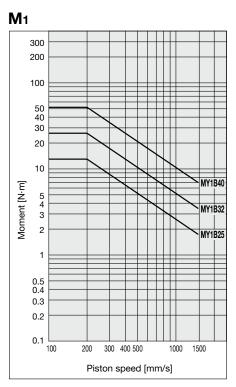
3. For detailed selection procedures, refer to pages 7 and 8.

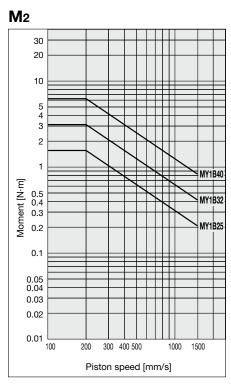


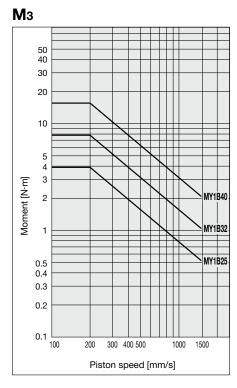
#### Maximum Allowable Moment/Maximum Load Mass

#### **Maximum Allowable Moment**

Select the moment from within the range of operating limits shown in the graphs. Note that the maximum load mass value may sometimes be exceeded even within the operating limits shown in the graphs. Therefore, also check the load mass for the selected conditions.

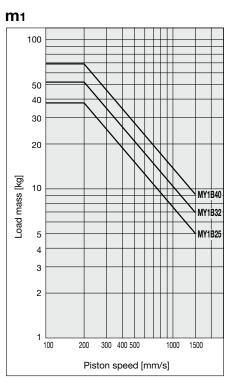


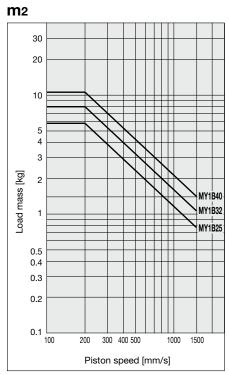


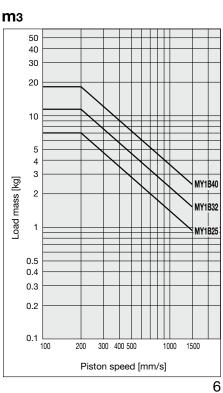


#### **Maximum Load Mass**

Select the load mass from within the range of limits shown in the graphs. Note that the maximum allowable moment value may sometimes be exceeded even within the operating limits shown in the graphs. Therefore, also check the allowable moment for the selected conditions.







# **Model Selection**

Following are the steps for selecting the most suitable MY1B series to your application.

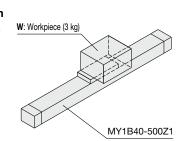
#### **Calculation of Guide Load Factor**

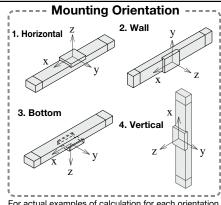
#### 1. Operating Conditions -

Cylinder ..... MY1B40-500Z1

Average operating speed  $0a \cdots 300 \text{ mm/s}$ 

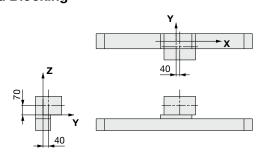
Mounting orientation ..... Horizontal





For actual examples of calculation for each orientation, refer to the **Web Catalog**.

#### 2. Load Blocking



#### Mass and Center of Gravity for Workpiece

Workpiece no.	Mass	Center of gravity							
	m	<b>X</b> -axis	<b>Y</b> -axis	<b>Z</b> -axis					
W	3 kg	40 mm	40 mm	70 mm					

#### 3. Calculation of Load Factor for Static Load

m<sub>1</sub>: Mass

**m**<sub>1</sub> **max** (from ① of graph MY1B/**m**<sub>1</sub>) = 46 [kg]······

Load factor  $\Omega_1 = m_1/m_1 \max = 3/46 = 0.07$ 

M<sub>1</sub>: Moment

**M**<sub>1</sub> **max** (from ② of graph MY1B/**M**<sub>1</sub>) = 35 [N·m]······

 $\mathbf{M}_1 = \mathbf{m}_1 \times \mathbf{g} \times \mathbf{X} = 3 \times 9.8 \times 40 \times 10^{-3} = 1.18 [\text{N} \cdot \text{m}]$ 

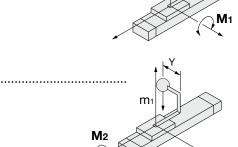
Load factor  $\Omega_2 = M_1/M_1 max = 1.18/35 = 0.04$ 

M<sub>2</sub>: Moment

**M₂ max** (from ③ of graph MY1B/**M₂**) = 4.2 [N·m]······

 $M_2 = m_1 \times g \times Y = 3 \times 9.8 \times 40 \times 10^{-3} = 1.18 [N \cdot m]$ 

Load factor  $\Omega_3 = M_2/M_2 \max = 1.18/4.2 = 0.29$ 



#### 4. Calculation of Load Factor for Dynamic Moment -

#### Equivalent load FE at impact

$$\mathbf{F}_{E} = 1.4 \text{ Va} \times \delta \times \mathbf{m} \times \mathbf{g} = 1.4 \times 300 \times \frac{1}{100} \times 3 \times 9.8 = 123.5 \text{ [N]}$$

M<sub>1E</sub>: Moment

**M**<sub>1E</sub> max (from ④) of graph MY1B/M<sub>1</sub> where  $1.4 \text{ } \text{0} \text{a} = 420 \text{ } \text{mm/s}) = 25 \text{ } [\text{N} \cdot \text{m}] \cdots$ 

**M**<sub>1E</sub> = 
$$\frac{1}{3}$$
 x **F**<sub>E</sub> x **Z** =  $\frac{1}{3}$  x 123.5 x 70 x 10<sup>-3</sup> = 2.89 [N·m]

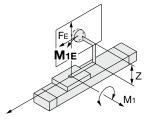
Load factor  $OL_4 = M_1 E/M_1 E max = 2.89/25 = 0.12$ 

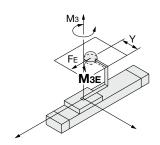
MзE: Moment

M<sub>3E</sub> max (from 5) of graph MY1B/M<sub>3</sub> where 1.410a = 420 mm/s) = 7.4 [N·m]·············

**М**зе = 
$$\frac{1}{3}$$
 x **F**e x **Y** =  $\frac{1}{3}$  x 123.5 x 40 x 10<sup>-3</sup> = 1.65 [N·m]

Load factor 0.5 = M3E/M3E max = 1.65/7.4 = 0.23





#### 5. Sum and Examination of Guide Load Factors

$$\sum \alpha = \Omega_1 + \Omega_2 + \Omega_3 + \Omega_4 + \Omega_5 = 0.75 \le 1$$

The above calculation is within the allowable value, and therefore the selected model can be used.

Select a shock absorber separately.

In an actual calculation, when the total sum of guide load factors  $\sum \alpha$  in the formula above is more than 1, consider either decreasing the speed, increasing the bore size, or changing the product series.

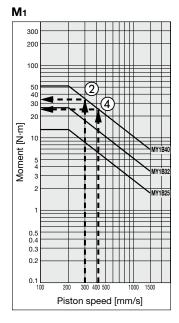
#### **Load Mass**

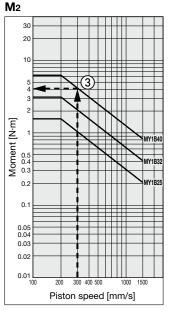
 $m_1$ 

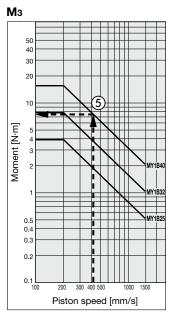
# 

Piston speed [mm/s]

#### Allowable Moment







# **Mechanically Jointed Rodless Cylinder**

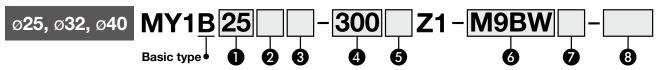
# **Basic Type**

# IY1B Series

Ø25, Ø32, Ø40



#### How to Order



#### Bore size

	25	25 mm
ĺ	32	32 mm
	40	40 mm

#### 3 Piping

<u> </u>	
Nil	Standard type
G	Centralized piping type

#### 5 Stroke adjustment unit symbol For stroke adjustment units, refer to page 10.

Nil Without auto switch (Built-in magnet) Refer to the table below for the applicable

6 Auto switch

auto switch model.

#### 2 Port thread type

Symbol	Type
Nil	Rc
TN	NPT
TF	G

#### 4 Cylinder stroke [mm]

Bore size	Standard stroke	Max. manufacturable stroke
25	100, 200, 300, 400	
32	500, 600, 700, 800 900, 1000, 1200, 1400	5000
40	1600, 1800, 2000	

- \* The stroke can be manufactured in 1 mm increments from 1 mm stroke.
- \* Please be advised that with a stroke of 49 mm or less, there are cases where auto switch mounting is not possible, and the performance of the air cushion may decline.

Scan or click here.

#### Number of auto switches

Nil	2
S	1
n	n

#### Made to Order Common Specifications (For details, refer to the Web Catalog.)

Symbol	Specifications
-XB22	Shock absorber soft type RJ series mounted
-X168	Helical insert thread specifications

#### Applicable Auto Switches / Refer to the Web Catalog for further information on auto switches.

			light		Load volta		ge	Auto swit	ch model	Lead	wire l	engtl														
Тур	e Special function	Electrical entry	Indicator light	Wiring (Output)			AC	Perpendicular	In-line	0.5 (Nil)	1 (M)	3 (L)	1 5	Pre-wired connector	Applical	ble load										
				3-wire (NPN)		5 V, 12 V		M9NV	M9N			•	0	0	IC circuit											
switch	_			3-wire (PNP)		3 V, 12 V		M9PV	M9P	•		•	0	0	IC CIrcuit											
S				2-wire		12 V	]	M9BV	М9В	•	•	•	0	0	_											
auto			3-wire (NPN) Yes 3-wire (PNP)	3-wire (NPN)	3-wire (NPN)				ĺ		5 V, 12 V	5 V 10 V		M9NWV	M9NW	•	•	•	0	0	IC circuit	_				
a a	Diagnostic indication (2-color indicator)	indicator)  Grommet   Yes   3-wire (PNP)   24  2-wire   3-wire (NPN)		3-wire (PNP)	NP) 24 V	4 V   5 V, 12 V	<b>'</b>   -	M9PWV	M9PW	•	•	•	0	0		Relay, PLC										
state	(2 color maleator)			12 V	]	M9BWV	M9BW	•	•	•	0	0	_	1 20												
s p				3-wire (NPN)	e (NPN)	5 V, 12 V		M9NAV*1	M9NA*1	0	0	•	0	0	IC circuit											
Solid	Water resistant (2-color indicator)			3-wire (PNP)	3 V, 12 V		(PNP)			M9PAV*1 M9PA*1		0	0	•	0	0	IC CIrcuit									
	(2 color indicator)					2-wire		12 V		M9BAV*1	M9BA*1	0	0	•	0	0	_									
Reed		Crommet	Yes	3-wire (NPN equiv.)	_	5 V	-	A96V	A96	•	•	•	•	0	IC circuit	-										
æ .	2	Grommet		Grommet	Grommet	Groinmet	Grornmet	Grommet	Grommet	Grommet	Grommet	Grommet		2 wire	041/	12.1/	100 V	A93V	A93	•	•	•	•	O*2	_	Relay,
	B C C C C C C C C C C C C C C C C C C C			No	2-wire	24 V	12 V	100 V or less	A90V	A90	•	•	•	•	O*2	IC circuit	PLC									

<sup>\*1</sup> Water-resistant type auto switches can be mounted on the above models, but SMC cannot guarantee water resistance.

\* Lead wire length symbols: 0.5 m ······· Nil (Example) M9NW 1 m ..... M (Example) M9NWM 3 m ..... L (Example) M9NWL (Example) M9NWZ

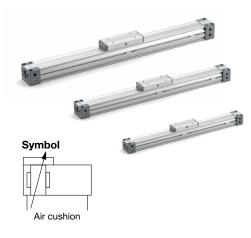
<sup>\*2</sup> The load voltage used is 24 VDC.

<sup>\*</sup> For details on auto switch mounting brackets and part numbers, refer to page 19.

<sup>\*</sup> Auto switches marked with a "O" are produced upon receipt of order.

Auto switches are shipped together with the product but do not come assembled.

# Mechanically Jointed Rodless Cylinder MY1B Series



#### **Specifications**

Вог	re size [mm]	25	32	40			
Fluid		Air					
Action		Double acting					
Operating	pressure range	0.1 to 0.8 MPa					
Proof pres	sure	1.2 MPa					
Ambient an	d fluid temperatures	5 to 60°C					
Cushion		Air cushion					
Lubrication	1		Non-lube				
Stroke leng	gth tolerance	2700 or less $^{+1.8}_{0.}$ , 2701 to 5000 $^{+2.8}_{0.}$					
Piping	Front/Side port	1,	1/4				
port size	Bottom port	Ø	Ø6				

#### **Piston Speed**

	Bore size [mm]	25 to 40
Without stroke adjustment u	nit	100 to 1000 mm/s
Stroke	A unit	100 to 1000 mm/s*1
adjustment unit	L unit and H unit	100 to 1500 mm/s*2

- \*1 Be aware that when the stroke adjustment range is increased with the adjustment bolt, the air cushion capacity decreases. Also, when exceeding the air cushion stroke ranges on page 11, the piston speed should be 100 to 200 mm/s.
- \*2 The piston speed is 100 to 1000 mm/s for centralized piping.
- \* Use at a speed within the absorption capacity range. Refer to page 11.
- \* Due to the construction of this product, it may have more fluctuation in operating speed compared to a rod type air cylinder. For applications that require constant speed, select the equipment corresponding to the required level.

#### **Stroke Adjustment Unit Specifications**

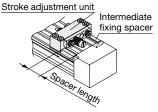
Bore	size [mm]		25			32			40			
Unit symbol		Α	L	Н	Α	L	Н	Α	L	Н		
Configuration Shock absorbe	r model	With adjustment bolt	RB 1007 + with adjustment bolt	RB 1412 + with adjustment bolt	With adjustment bolt	RB 1412 + with adjustment bolt	RB 2015 + with adjustment bolt	With adjustment bolt	RB 1412 + with adjustment bolt	RB 2015 + with adjustment bolt		
Stroke adjustment range by	Without spacer	0 to -11.5				0 to -12		0 to -16				
intermediate	With short spacer		–11.5 to –23			-12 to -24			-16 to -32			
fixing spacer [mm]	With long spacer		-23 to -34.5			-24 to -36			-32 to -48			

<sup>\*</sup> Stroke adjustment range is applicable for one side when mounted on a cylinder.

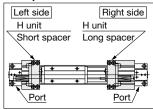
#### Stroke Adjustment Unit Symbol

$\overline{}$		ajaotinoni (		,										
`				Right side stroke adjustment unit										
			Without	A: With	adjustm	ent bolt	L: With lov + Adjustm		k absorber		H: With high load shock absorber + Adjustment bolt			
			unit		With short spacer	With long spacer		With short spacer	With long spacer		With short spacer	With long spacer		
unit	Wit	thout unit	Nil	SA	SA6	SA7	SL	SL6	SL7	SH	SH6	SH7		
Ħ	A: With a	djustment bolt	AS	Α	AA6	AA7	AL	AL6	AL7	AH	AH6	AH7		
ner		With short spacer	A6S	A6A	A6	A6A7	A6L	A6L6	A6L7	A6H	A6H6	A6H7		
adjustment		With long spacer	A7S	A7A	A7A6	A7	A7L	A7L6	A7L7	A7H	A7H6	A7H7		
adj	L: With low lo	oad shock absorber +	LS	LA	LA6	LA7	L	LL6	LL7	LH	LH6	LH7		
ş	Adjustment	With short spacer	L6S	L6A	L6A6	L6A7	L6L	L6	L6L7	L6H	L6H6	L6H7		
stroke	bolt	With long spacer	L7S	L7A	L7A6	L7A7	L7L	L7L6	L7	L7H	L7H6	L7H7		
side	H: With high I	load shock absorber +	HS	HA	HA6	HA7	HL	HL6	HL7	Н	HH6	HH7		
eft si	Adjustment	With short spacer	H6S	H6A	H6A6	H6A7	H6L	H6L6	H6L7	Н6Н	H6	Н6Н7		
F	bolt	With long spacer	H7S	H7A	H7A6	H7A7	H7L	H7L6	H7L7	H7H	H7H6	H7		

# Stroke adjustment unit mounting diagram



#### **Example of H6H7 attachment**



- \* Spacers are used to fix the stroke adjustment unit at an intermediate stroke position.
- For details on spacers and stroke adjustment units, refer to "Accessory Brackets (Option)" on page 16.
- \* For precautions, refer to page 20.

#### **Accessory Brackets (Option)**

Stroke adjustment unit	p. 16
Side support	p. 17
Floating bracket	p. 18

Refer to page 19 for the specifications with auto switch.



#### Shock Absorbers for L and H Units

Model	Stroke adjustment	Bore size [mm]						
Model	unit	25	32	40				
Standard (Shock absorber	L	RB1007	RB1	412				
RB series)	Н	RB1412	RB2	2015				
Shock absorber soft type	L	RJ1007H	RJ14	112H				
RJ series mounted (-XB22)	Н	RJ1412H	_	_				

- \* The shock absorber service life is different from that of the MY1B cylinder depending on operating conditions. Refer to the RB/RJ Series Specific Product Precautions for the replacement period.
- Shock absorber soft type RJ series mounted (-XB22) is made-to-order common specifications. For details, refer to the Web Catalog.

#### **Shock Absorber Specifications**

Mode	I	RB 1007	RB 1412	RB 2015
Max. absorbed e	nergy [J]	5.9	19.6	58.8
Stroke absorption	n [mm]	7	12	15
Max. collision sp	eed [mm/s]	1500	1500	1500
Max. operating freque	ncy [cycle/min]	70	45	25
Spring force [N]	Extended	4.22	6.86	8.34
Spring force [N]	Retracted	6.86	15.98	20.50
Operating temperat	ure range [°C]		5 to 60	

<sup>\*</sup> The shock absorber service life is different from that of the MY1B cylinder depending on operating conditions. Refer to the RB Series Specific Product Precautions for the replacement period.

#### **Theoretical Output**

								[N]			
Bore size	Piston area	a processing [contact of contact									
[mm]	[mm <sup>2</sup> ]	0.2	0.3	0.4	0.5	0.6	0.7	0.8			
25	490	98	147	196	245	294	343	392			
32	804	161	241	322	402	483	563	643			
40	1256	251	377	502	628	754	879	1005			

<sup>\*</sup> Theoretical output [N] = Pressure [MPa] x Piston area [mm²]

#### Weight

Unit: kg Stroke adjustment unit Side support Additional Weight weight weight Bore Basic weight per of (per set) (per unit) size 50 mm of moving weight [mm] A/B type A unit L unit H unit stroke parts weight weight weight weight 25 0.91 0.10 0.25 0.02 0.06 0.10 0.18 32 1.74 0.16 0.52 0.02 0.12 0.21 0.40 40 3.04 0.24 0.93 0.04 0.23 0.32 0.49

Calculation: (Example) MY1B25-300AZ1

Weight of A unit · · · · · · 0.06 kg

#### **Cushion Capacity**

#### **Cushion Selection**

#### <Air cushion>

Air cushions are a standard feature on mechanically jointed rodless cylinders.

The air cushion mechanism is incorporated to prevent excessive impact of the piston with high kinetic energy at the stroke end. The purpose of air cushion, thus, is not to decelerate the piston near the stroke end.

The ranges of load and speed that air cushions can absorb are within the air cushion limit lines shown in the graphs.

#### <Stroke adjustment unit with shock absorber>

Use this unit when operating with a load and speed exceeding the air cushion limit line, or when cushioning is required outside of the effective air cushion stroke range due to stroke adjustment.

#### L unit

Use this unit when cushioning is required outside of the effective air cushion range even if the load and speed are within the air cushion limit line, or when the cylinder is operated in a load and speed range above the air cushion limit line and below the L unit limit line.

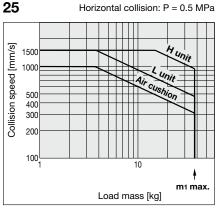
#### H unit

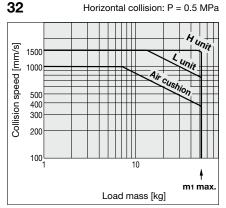
Use this unit when the cylinder is operated in a load and speed range above the L unit limit line and below the H unit limit line.

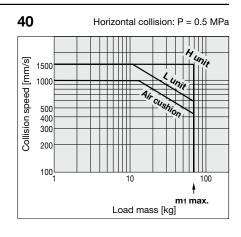
- For details on stroke adjustment using the adjustment bolt, refer to the Web Catalog.
- \* Do not use a shock absorber together with air cushion.
- $\ast\,$  When using the shock absorber, use it with the cushion needle fully open.

Air Cushion St	Air Cushion Stroke								
Bore size [mm]	Cushion stroke								
25	15								
32	19								
40	24								

#### **Absorption Capacity of Air Cushion and Stroke Adjustment Units**

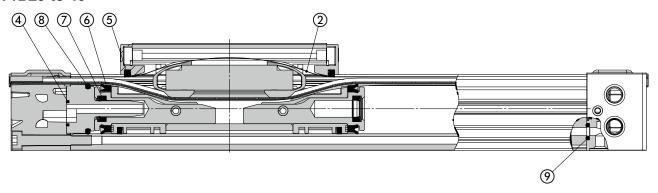


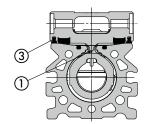




#### Construction

#### MY1B25 to 40





#### **Component Parts/Seal Kit**

No.	Description	Material Qty.		MY1B25	MY1B32	MY1B40		
1 5	Seal belt	Urethane	1	MY25-16C-Stroke	MY32-16C- Stroke	MY40-16C- Stroke		
2	Dust seal band	Stainless steel	1	MY1B25-16B- Stroke	MY1B32-16B- Stroke	MY1B40-16B- Stroke		
3	Side scraper	Polyamide	2	MYB25-15BA5900B	MYB32-15BA5901B	MYB40-15BA5902B		
4 (	Cushion boss gasket	NBR	2	MYB25-16GA5900	MYB32-16GA5901	MYB40-16GA5902		
5	Scraper	NBR	2					
6	Piston seal	NBR	2					
7	Cushion seal	NBR	2	MY1B25-PS	MY1B32-PS	MY1B40-PS		
8	Tube gasket	NBR	2					
9 (	O-ring	NBR	4					

<sup>\*</sup> Seal kit includes ⑤, ⑥, ⑦, ⑧, and ⑨. Order the seal kit based on each bore size.

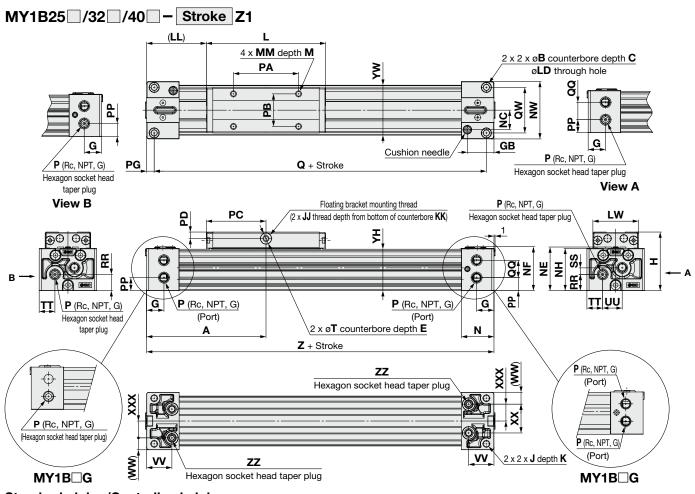
When ① and ② are shipped independently, a grease pack is included. (10 g per 1000 mm stroke) Order with the following part number when only the grease pack is needed.

Grease pack part number: GR-S-010 (10 g), GR-S-020 (20 g)



Seal kit includes a grease pack (10 g).

#### **Standard Type/Centralized Piping Type**



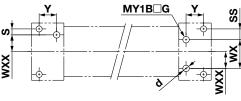
Standard	andard piping/Centralized piping [mm]																						
Model	Α	В	С	E	G	GB	Н	J	JJ	K	KK	L	LD	LL	LW	М	MM	N	NC	NE	NF	NH	NW
MY1B25□	110	9	5.5	2	16	24.5	54	M6 x 1	M5 x 0.8	9.5	7.6	110	5.4	55	42	9	M5 x 0.8	30	18	40.2	40.5	39	53
MY1B32□	140	11	6.6	2	19	28.5	68	M8 x 1.25	M5 x 0.8	16	10	140	6.8	70	52	12	M6 x 1	37	22	50.2	50	49	64
MY1B40□	170	14	8.5	2	23	35	84	M10 x 1.5	M6 x 1	15	13	170	8.6	85	64	12	M6 x 1	45	26.5	62.7	62	61.5	75

Model	Р	PA	PB	PC	PD	PP	PG	Q	QW	RR	Т	TT	W	ww	XXX	ΥH	YW	Z	ZZ
MY1B25□	1/8	60	30	55	6	12	7	206	42	15	10	14.5	23.3	11	15.5	38.2	46	220	Rc1/16
MY1B32□	1/8	80	35	70	10	16	8	264	51	16	10	16	28.5	12	20	48	55	280	Rc1/16
MY1B40□	1/4	100	40	85	12	18.5	9	322	59	23.5	14	20	35	14	23.5	60.5	67	340	Rc1/8

#### **Centralized piping**

Model	QQ	SS	UU	XX
MY1B25□	16	6	18	26.5
MY1B32□	16	11	32	40
MY1B40□	24	12	35	47

#### **Centralized Piping on the Bottom**



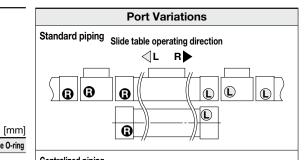


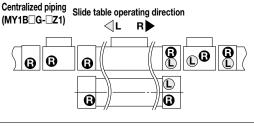
Bottom ported (ZZ) (Applicable O-ring)

\* This figure shows the recommended machining dimensions of the mounting surface when viewed from the cylinder side.

Model	WXX	Υ	S	d	D	R	Applicable O-ring
MY1B25□	15.5	16.2	5.5	6	11.4	1.1	11.5 x 8.5 x 1.5
MY1B32□	20	20.4	5.5	6	11.4	1.1	11.5 x 6.5 x 1.5
MY1B40□	23.5	25.9	6	8	13.4	1.1	13.7 x 10.7 x 1.5

		[mm]
Model	WX	SS
MY1B25□	26.5	10
MY1B32□	40	5.5
MY1B40	47	6

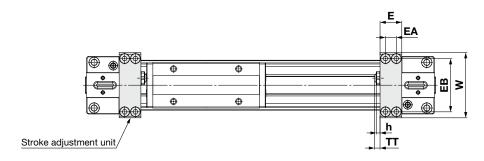


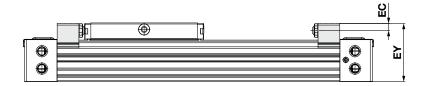


#### **Stroke Adjustment Units**

#### With adjustment bolt

MY1B Bore size — Stroke AZ1



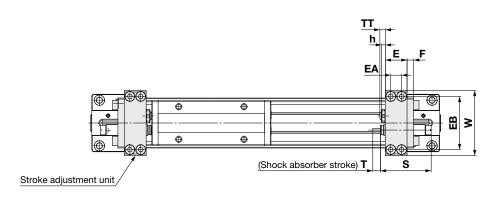


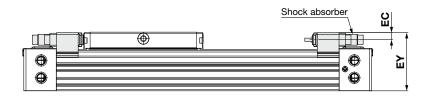


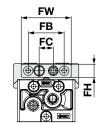
										[HIIII]
Ap	plicable cylinder	Е	EA	EB	EC	EY	FC	h	TT	W
П	MY1B25	20	10	49	6.5	53.5	13	3.5	5 (Max. 16.5)	60
ı	MY1B32	25	12	61	8.5	67	17	4.5	8 (Max. 20)	74
	MY1B40	31	15	76	9.5	81.5	17	4.5	9 (Max. 25)	94

#### With low load shock absorber + Adjustment bolt

MY1B Bore size — Stroke LZ1





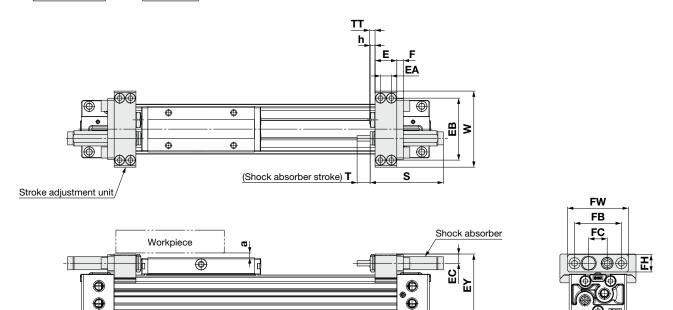


																[mm]
Applicable cylinder	Е	EA	EB	EC	EY	F	FB	FC	FH	FW	h	S	Т	TT	W	Shock absorber model
MY1B25	20	10	49	6.5	53.5	6	33	13	12	46	3.5	46.7	7	5 (Max. 16.5)	60	RB1007
MY1B32	25	12	61	8.5	67	6	43	17	16	56	4.5	67.3	12	8 (Max. 20)	74	RB1412
MY1B40	31	15	76	9.5	81.5	6	43	17	16	56	4.5	67.3	12	9 (Max. 25)	94	RB1412

#### **Stroke Adjustment Units**

With high load shock absorber + Adjustment bolt

MY1B Bore size — Stroke HZ1

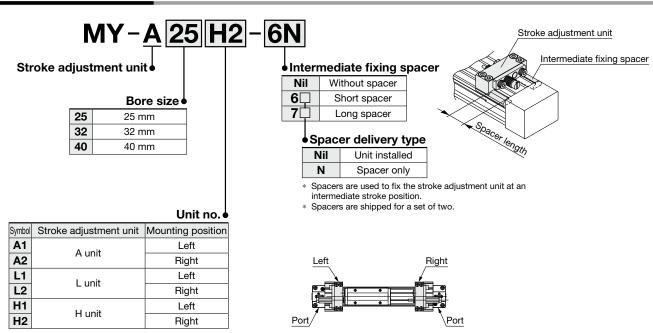


\* Since the EY dimension of H unit is longer than the table top height (H dimension), when mounting a workpiece that exceeds the overall length (L dimension) of the slide table, allow a clearance of dimension "a" or longer on the workpiece side.

																	[]
Applicable cylinder	Е	EA	EB	EC	EY	F	FB	FC	FH	FW	h	S	Т	TT	W	Shock absorber model	а
MY1B25	20	10	57	8.5	57.5	6	43	17	16	56	4.5	67.3	12	5 (Max. 16.5)	70	RB1412	4.5
MY1B32	25	12	74	11.5	73	8	57	22	22	74	5.5	73.2	15	8 (Max. 20)	90	RB2015	6
MY1B40	31	15	82	12	87	8	57	22	22	74	5.5	73.2	15	9 (Max. 25)	100	RB2015	4

# **Accessory Brackets (Option)**

#### **Stroke Adjustment Units**

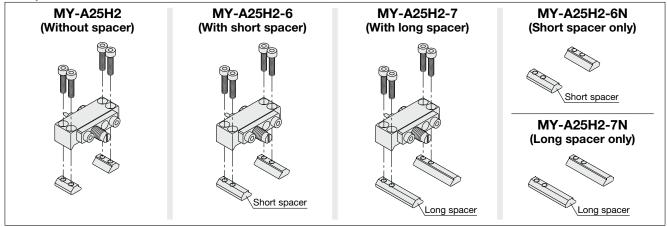


#### Stroke adjustment range

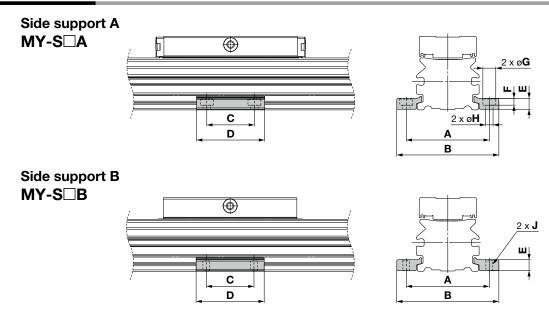
Stroke adjustifier	broke adjustifier range											
Bore size	25				32		40					
Unit symbol	Α	A L H A				Н	Α	L	Н			
Without spacer	С	0 to -11.5			0 to -12	2	0 to -16					
With short spacer	-1	-11.5 to -23			12 to –2	24	−16 to −32					
With long spacer	-23 to -34.5			_	24 to -3	36	-32 to -48					

Spacer length			[mm
Bore size	25	32	40
Short spacer	11.5	12	16
Long spacer	23	24	32

#### **Component Parts**



#### **Side Supports**



Model	Applicable cylinder	Α	В	С	D	Е	F	G	Н	J
MY-S25A	MY1B25	61	75	35	50	8	5	9.5	5.5	M6 x 1
IVI 1-323 <sub>B</sub>	MY1B32	70	84	33	50	0	5	9.5	5.5	IVIOXI
MY-S32 <sup>A</sup> <sub>B</sub>	MY1B40	87	105	45	64	11.7	6	11	6.6	M8 x 1.25

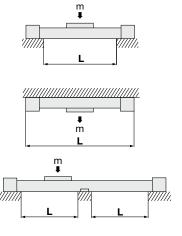
<sup>\*</sup> Side supports consist of a set of right and left brackets.

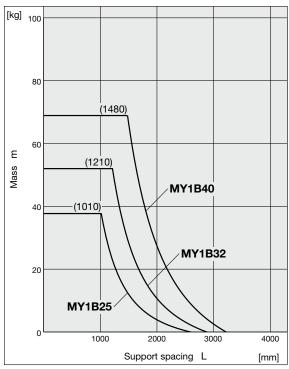
#### **Guide for Side Support Application**

For long stroke operation, the cylinder tube may be deflected depending on its own weight and the load. In such a case, use a side support in the middle section. The spacing (L) of the support must be no more than the values shown in the graph on the right.

## **⚠** Caution

- 1. If the cylinder mounting surfaces are not measured accurately, using a side support may cause poor operation. Therefore, be sure to level the cylinder tube when mounting it. Also, for long stroke operation involving vibration and impact, the use of a side support is recommended even if the spacing value is within the allowable limits shown in the graph.
- **2.** Support brackets are not for mounting; use them solely for providing support.





#### Floating Brackets

Facilitates connection to other guide systems.

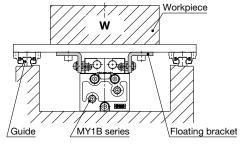
Applicable bore size

#### ø**25,** ø**32,** ø**40**

#### MY J25/MY J32/MY J40

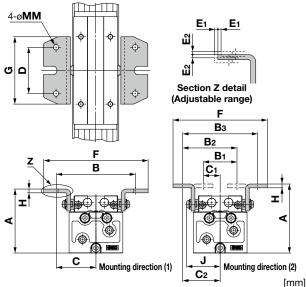
#### L Type

#### **Application Example**



#### **Mounting Dimensions**

One set of brackets can be mounted in two directions for compact combinations.



Part no.	Applicable		С	ommo	on	Mounting direction (1)				
Part no.	cylinder	D	G	Н	J	MM	Α	В	С	F
MY-J25	MY1B25□	40	60	3.2	35	5.5	63	78	39	100
<b>MY-J32</b>	MY1B32□	55	80	4.5	40	6.5	76	94	47	124
MY-J40	MY1B40□	74	100	4.5	47	6.5	92	112	56	144

Part no.	Applicable		Mounting direction (2)								
Part IIO.	cylinder	Α	B <sub>1</sub>	B <sub>2</sub>	Вз	C <sub>1</sub>	C <sub>2</sub>	F	E <sub>1</sub>	E <sub>2</sub>	
MY-J25	MY1B25□	65	28	53	78	14	39	96	1	1	
MY-J32	MY1B32□	82	40	64	88	20	44	111	1	1	
MY-J40	MY1B40□	98	44	76	108	22	54	131	1	1	

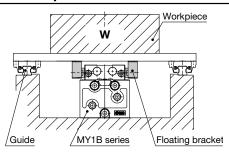
- \* Floating brackets consist of a set of right and left brackets.
- \* For details on how to secure the holding bolt, refer to the operation manual.

#### MY-J25 to 40 (1 set) Component Parts

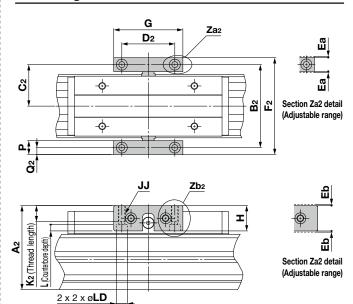
Description	Qty.	Material
Bracket	2	Carbon steel
Pin	2	Carbon steel
Conical spring washer	2	Carbon steel
Holding bolt	2	Chromium molybdenum steel

#### **Block Type**

#### **Application Example**



#### **Mounting Dimensions**



										[mm]
Part no.	Applicable	G	Н	J			PL	LD	Adjustable range	
rait iio.	cylinder	G	п	ر ا	J	_		בט	Ea	Eb
MYAJ25	MY1B25□	55	22	M6	x 1	5.5	12	9.5	1	1
MYAJ32	MY1B32□	60	22	M6	x 1	5.5	12	9.5	1	1
MYAJ40	MY1B40□	72	32	M8 x	1.25	6.5	16	11	1	1
Part no.	Applicable	<b>A</b> 2	<b>B</b> 2	C <sub>2</sub>	D <sub>2</sub>	F <sub>2</sub>	<b>K</b> 2	Q <sub>2</sub>		
raitiio.	cylinder	AZ	D2	02	D2	Γ2	I\2	Q Z		
MYAJ25	MY1B25□	63	61	30.5	40	73	14	6		
MYAJ32	MY1B32□	73	72	36	46	84	14	6		
MYAJ40	MY1B40□	93.5	88	44	55	104	19	8		

<sup>\*</sup> For details on how to secure the holding bolt, refer to the operation manual.

#### MYAJ25 to 40 (1 set) Component Parts

Description	Qty.	Material
Bracket	2	Rolled steel
Pin	2	Carbon steel
Conical spring washer	2	Carbon steel
Holding bolt	2	Chromium molybdenum steel



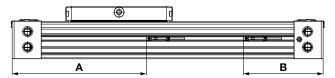
# MY1B Series D-M9 D-A9

# **Auto Switch Mounting**



#### **Auto Switch Proper Mounting Position (Detection at stroke end)**

#### MY1B (Basic type)



#### **Auto Switch Proper Mounting Position**

Auto Switch Proper Mounting Position [mm]						
Auto switch model	D-M9 D-M9	D□V D□W D□WV	D-A9□ D-A9□V			
Bore size	Α	В	Α	В		
25	138	82	134	86		
32	186.5	93.5	182.5	97.5		
40	222.5	117.5	218.5	121.5		

 $<sup>\</sup>ast\,$  Adjust the auto switch after confirming the operating conditions in the actual setting.

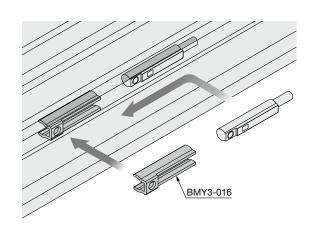
#### **Operating Range**

\* Values which include hysteresis are for reference purposes only. They are not a guarantee (assuming approximately ±30% dispersion) and may change substantially depending on the ambient environment.

			[mm]			
Auto switch model	Bore size					
	25	32	40			
D-M9□/M9□V D-M9□W/M9□WV D-M9□A/M9□AV	5.0	5.5	5.5			
D-A9□/A9□V	7.0	10.0	9.0			

#### Auto Switch Mounting Bracket/Part No.

Auto switch model	Part no.			
D-M9□/M9□V D-M9□W/M9□WV D-M9□A/M9□AV D-A9□/A9□V	BMY3-016			





# MY1B Series Specific Product Precautions

Be sure to read this before handling the products. Refer to the back cover for safety instructions. For actuator and auto switch precautions, refer to the "Handling Precautions for SMC Products" and the "Operation Manual" on the SMC website: https://www.smcworld.com

#### Selection

#### **⚠** Caution

#### 1. Cautions on less frequent operation

When the cylinder is used extremely infrequently, operation may be interrupted in order for anchoring and a change lubrication to be performed or service life may be reduced.

#### 2. Air leakage

Due to the mechanically jointed rodless cylinder's special seal construction, a small amount of air leakage that does not affect the thrust will occur. A subtle "hissing" sound may be heard as a result.

#### Mounting

## **⚠** Caution

 Do not generate negative pressure in the cylinder tube.

When the cylinder is in a non-pressurized state, such as during a test run, maintenance, etc., external or inertial force may cause negative pressure to be generated inside the cylinder. In such cases, the seal belt may come off, resulting in a temporary air leak.

- Examples:
- 1) When external force is used to move a slide table all at once during installation, a test run, etc.
- When a vertically-mounted slide table carrying a load drops due to its weight
  - (In either case, the smaller the speed controller's opening is set, the more likely negative pressure is to be generated.)
- For negative pressure prevention
- When using external force to move a slide table, move it slowly and steadily at about 20 mm/s. (If the speed controller's opening is set extremely small, increase the opening only during manual operation.)
- If the seal belt comes off
- If the seal belt comes off due to negative pressure and the air is leaking, manually move the slide table from the beginning to the end of the cylinder's full stroke slowly and steadily at about 20 mm/s.
- (If the speed controller's opening is set extremely small, increase the opening only during manual operation.)

#### **Operating Environment**

# **⚠** Warning

- Do not use in an environment where the cylinder is exposed to coolant, cutting oil, water drops, adhesive foreign matter, dust, etc. and avoid use with compressed air containing drainage and foreign matter.
  - Foreign matter or liquids on the cylinder's interior or exterior can wash out the lubricating grease, which can lead to deterioration and damage of dust seal band and seal materials, causing a danger of malfunction.

When operating in locations with exposure to water and oil, or in dusty locations, provide protection such as a cover to prevent direct contact with the cylinder, or mount so that the dust seal band surface faces downward, and operate with clean compressed air.

#### Service Life and Replacement Period of Shock Absorber

#### **⚠** Caution

 The cylinder, equipment and/or workpieces might be destroyed if the table collides the end of the stroke without being buffered properly by the shock absorber. See below for the number of cycles that are possible within the catalog usage range (model selection graph range), and check the operating conditions periodically, adjusting or replacing the shock absorber when necessary.

RB10□□ to RB1412: 2 million times

\* Specified service life (suitable replacement period) is the value at room temperature (20 to 25°C). The period may vary depending on the temperature and other conditions. In some cases, the shock absorber may need to be replaced before the allowable operating cycle above.



# **⚠** Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of "Caution," "Warning" or "Danger." They are all important notes for safety and must be followed in addition to International Standards (ISO/IEC)\*1), and other safety regulations.

⚠ Danger: Danger indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.

⚠ Warning: Warning indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury.

Caution: Caution indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury.

\*1) ISO 4414: Pneumatic fluid power - General rules and safety requirements for systems and their components ISO 4413: Hydraulic fluid power - General rules and safety requirements for systems and their components IEC 60204-1: Safety of machinery - Electrical equipment of machines - Part 1: General requirements ISO 10218-1: Robots and robotic devices - Safety requirements for industrial robots - Part 1:Robots

#### **.** Warning

1. The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications.

Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results. The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product. This person should also continuously review all specifications of the product referring to its latest catalog information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment.

2. Only personnel with appropriate training should operate machinery and equipment.

The product specified here may become unsafe if handled incorrectly. The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained

- 3. Do not service or attempt to remove product and machinery/ equipment until safety is confirmed.
  - 1. The inspection and maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway of the driven objects have been confirmed.
  - 2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions of all relevant products carefully.
  - 3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.
- 4. SMC products cannot be used beyond their specifications. They are not developed, designed, and manufactured to be used under the following conditions or environments. Use under such conditions or environments is not allowed.
  - 1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.
  - 2. Use for nuclear power, railways, aviation, space equipment, ships, vehicles, military application, equipment affecting human life, body, and property, combustion equipment, entertainment equipment, emergency shut-off circuits, press clutches, brake circuits, safety equipment, etc., and use for applications that do not conform to standard specifications such as catalogs and operation manuals.
  - 3. Use for interlock circuits, except for use with double interlock such as installing a mechanical protection function in case of failure. Please periodically inspect the product to confirm that the product is operating properly.

#### **⚠** Caution

SMC develops, designs, and manufactures products to be used for automatic control equipment, and provides them for peaceful use in manufacturing industries.

Use in non-manufacturing industries is not allowed.

Products SMC manufactures and sells cannot be used for the purpose of transactions or certification specified in the Measurement Act of each country. The new Measurement Act prohibits use of any unit other than SI units in

#### Limited warranty and Disclaimer/ Compliance Requirements

The product used is subject to the following "Limited warranty and Disclaimer" and "Compliance Requirements".

Read and accept them before using the product.

#### **Limited warranty and Disclaimer**

- 1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered, whichever is first.\*2) Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.
- 2. For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided. This limited warranty applies only to our product independently, and not to any other damage incurred due to the failure of the product.
- 3. Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalog for the particular products.
  - \*2) Suction cups (Vacuum pads) are excluded from this 1 year warranty. A suction cup (vacuum pad) is a consumable part, so it is warranted for a year after it is delivered.

Also, even within the warranty period, the wear of a product due to the use of the suction cup (vacuum pad) or failure due to the deterioration of rubber material are not allowed by the limited warranty.

#### Compliance Requirements

- 1. The use of SMC products with production equipment for the manufacture of weapons of mass destruction (WMD) or any other weapon is strictly prohibited.
- 2. The exports of SMC products or technology from one country to another are governed by the relevant security laws and regulations of the countries involved in the transaction. Prior to the shipment of a SMC product to another country, assure that all local rules governing that export are known and followed.

↑ Safety Instructions | Be sure to read the "Handling Precautions for SMC Products" (M-E03-3) and "Operation Manual" before use.